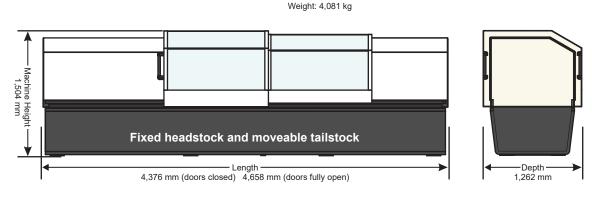


PRISM ENGRAVER **Specifications**

Machine Dimensions and Weight



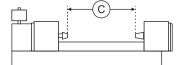
Cylinder Fixturing Options

Hollow Cylinder

Headstock: Direct Cone

Tailstock: Direct Cone





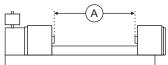
Max Overall Shafted (A) — Max Face Length (C) 1740 mm

Bore range 55 - 125 mm

Shafted Cylinder⁽³⁾

Headstock: 3-Jaw Chuck (200mm) Tailstock: 3-Jaw Chuck (200mm)

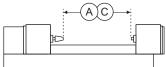




Max Overall Shafted (A) 1825 mm Max Face Length (B) 1700 mm Chuck throat diameter: 55 mm Shaft diameter 10 - 100 mm Max swallow depth: 79 mm **Both Shafted & Hollow**

Headstock: 3-Jaw Chuck with Cone Tailstock: 3-Jaw Chuck with Cone





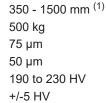
Max Overall Shafted (A) 1900 mm Max Face Length (C) 1300 mm*

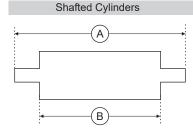
Bore Range 55 - 125 mm

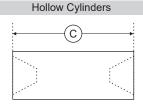
* Depends on selected cone

Cylinder Data

Circumference range Weight maximum Allowable cylinder taper ⁽²⁾ Allowable runout Copper hardness Deviation of copper hardness







(1) Maximum physical cylinder sizes. Engraveable Circumferences depend upon applied engrave head, engraving frequency, screen, and screen angle range. (2) See Site Survey 9800-3143 for complete machine details.

(3) These values assume a shafted cylinder with 300 mm shafts on both ends. To ensure fit, your cylinder drawings must be sent to Ohio GT. Weight does not include cylinder.



Specifications



Machine Technical Data			
Environmental Temperature	20 - 25°C, 40-65% relative humidity, non-condensing		
Heat dissipation	1.5kW		
Floor bowing under load	0.2 mm/m		
	Execution according to DIN 18202		
	Do not use intermediate floors or support beams as machine foundation		
Maximum allowable floor vibration	Peak to Peak Amplitude	Frequency	
	3.8 µm	2 - 8 Hz	
	2.5 µm	9 - 15 Hz	
	1.5 µm	16 - 21 Hz	
	1.0 µm	>21 Hz	
Connections			
	Power	Voltage	FrequencyFuse
Power supply	5.00 kVA	1x220V +/- 3%	50/60Hz +/- 1%25A
	5.00 kVA	1x230V +/- 3%	50/60Hz +/- 1%25A
	5.00 kVA	1x240V +/- 3%	50/60Hz +/- 1%25A
Communication	Ethernet for Collage Interface. Internet connection, ideally via Collage computer, for TeamViewer remote support is strongly suggested		

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